



# Machine Learning 1

Lecture 12.3 - Kernel Methods  
Gaussian Processes - Definition

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# Gaussian Processes

$$\begin{pmatrix} \vdots \\ 0 \\ \vdots \\ 0 \end{pmatrix} \sim N(\mu, \Sigma) \rightarrow \begin{pmatrix} \vdots \\ \cdot \end{pmatrix} \sim N(\cdot, \cdot)$$

## Definition (Gaussian Process):

stochastic process

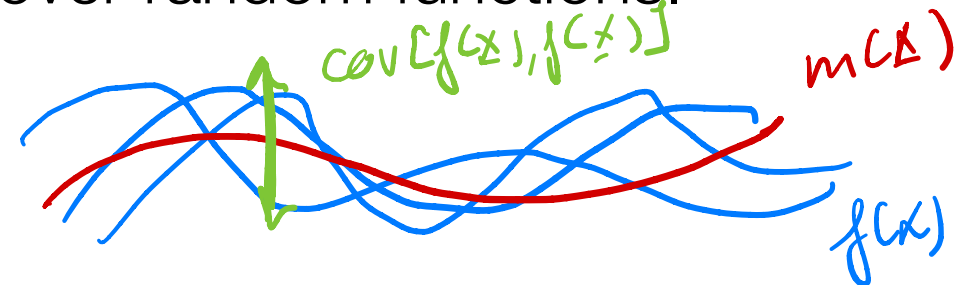
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A Gaussian process is a collection of random variables, any finite number of which is jointly Gaussian distributed

## Or put differently (functional viewpoint):

- Gaussian processes represent distributions over random functions.

$$f(\cdot) \sim GP(m(\cdot), k(\cdot, \cdot))$$



- The function evaluated at any specific input  $\mathbf{x}$  is a random variable  $f(\mathbf{x})$ , with

$$\mathbb{E}[f(\mathbf{x})] = m(\mathbf{x})$$

$$\text{cov}(f(\mathbf{x}), f(\mathbf{x}')) = \mathbb{E}[(f(\mathbf{x}) - m(\mathbf{x})) (f(\mathbf{x}') - m(\mathbf{x}'))] = k(\mathbf{x}, \mathbf{x}')$$

# Functional Viewpoint, why is this a GP?

- Take any finite set  $\{\mathbf{x}_1, \dots, \mathbf{x}_N\}$  with corresponding random variables  $\{f(\mathbf{x}_1), \dots, f(\mathbf{x}_N)\}$  then

$$p \left( \begin{bmatrix} f(\mathbf{x}_1) \\ \vdots \\ f(\mathbf{x}_N) \end{bmatrix} \right) = \mathcal{N} \left( \begin{bmatrix} m(\mathbf{x}_1) \\ \vdots \\ m(\mathbf{x}_N) \end{bmatrix}, \begin{bmatrix} k(\mathbf{x}_1, \mathbf{x}_1) & \dots & k(\mathbf{x}_1, \mathbf{x}_N) \\ \vdots & \ddots & \vdots \\ k(\mathbf{x}_N, \mathbf{x}_1) & \dots & k(\mathbf{x}_N, \mathbf{x}_N) \end{bmatrix} \right)$$

- Consistency requirement: any subset of  $\{f(\mathbf{x}_1), \dots, f(\mathbf{x}_N)\}$  should also be Gaussian distributed.
- But that works out because:

$$p \left( \begin{bmatrix} \mathbf{f}_1 \\ \mathbf{f}_2 \end{bmatrix} \right) = \mathcal{N} \left( \begin{bmatrix} \mathbf{m}_1 \\ \mathbf{m}_2 \end{bmatrix}, \begin{bmatrix} \mathbf{K}_{11} & \mathbf{K}_{12} \\ \mathbf{K}_{21} & \mathbf{K}_{22} \end{bmatrix} \right) \rightarrow p(\mathbf{f}_1) = \mathcal{N}(\mathbf{m}_1, \mathbf{K}_{11})$$

# Functions as vectors

- Think of a function  $f(\cdot)$  drawn from a  $GP$  as an extremely high-dimensional vector drawn from an extremely high-dimensional multivariate Gaussian distribution

- Each dimension corresponds to an element  $\mathbf{x} \in \mathbb{R}^n$

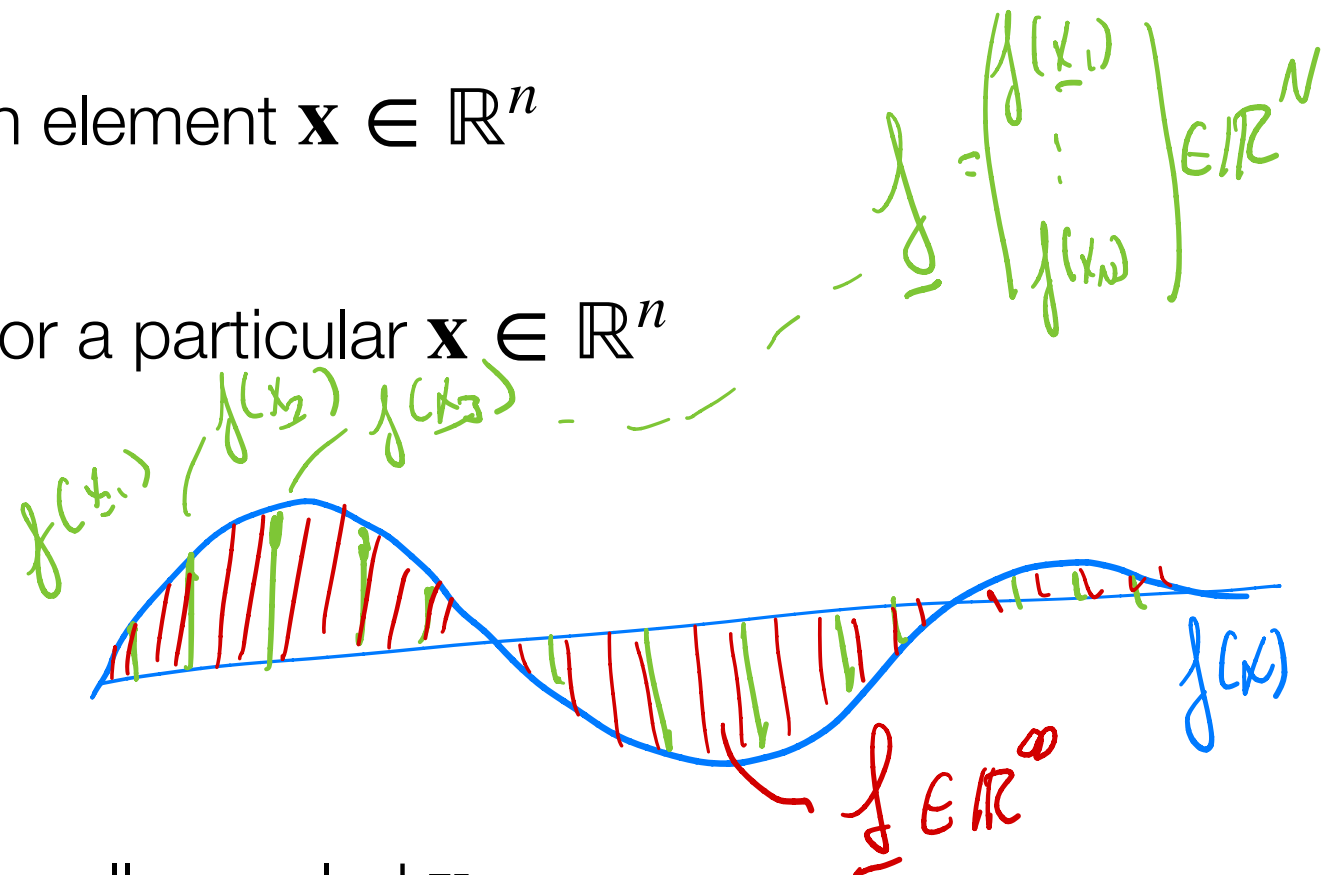
- Each entry of the vector is a  $f(\mathbf{x})$  for a particular  $\mathbf{x} \in \mathbb{R}^n$

- How do you sample from a  $GP$ :

- Sample input points  $\mathbf{x} \in \mathbb{R}^n$

- Construct the Gram matrix  $\mathbf{K}$  for all sampled  $\mathbf{x}$ .

- Sample vector. 
$$\begin{bmatrix} f(\mathbf{x}_1) \\ \vdots \\ f(\mathbf{x}_N) \end{bmatrix} \sim \mathcal{N} \left( \begin{bmatrix} m(\mathbf{x}_1) \\ \vdots \\ m(\mathbf{x}_N) \end{bmatrix}, \begin{bmatrix} k(\mathbf{x}_1, \mathbf{x}_1) & \dots & k(\mathbf{x}_1, \mathbf{x}_N) \\ \vdots & \ddots & \vdots \\ k(\mathbf{x}_N, \mathbf{x}_1) & \dots & k(\mathbf{x}_N, \mathbf{x}_N) \end{bmatrix} \right)$$



# Example: Bayesian Linear Regression

- Bayesian linear models:

$$f(\mathbf{x}) = \boldsymbol{\phi}(\mathbf{x})^T \mathbf{w}$$

- Prior on  $\mathbf{w}$ :

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{w} | \mathbf{0}, \boldsymbol{\Sigma}_p)$$

- Then  $f(\mathbf{x})$  is a Gaussian process

$$\mathbb{E}[f(\mathbf{x})] = \boldsymbol{\phi}(\mathbf{x})^T \mathbb{E}[\mathbf{w}] = \mathbf{0} = m(x)$$

$$\begin{aligned} \text{cov}(f(\mathbf{x}), f(\mathbf{x}')) &= \mathbb{E}[f(\mathbf{x})f(\mathbf{x}')] = \boldsymbol{\phi}(\mathbf{x})^T \mathbb{E}[\mathbf{w}\mathbf{w}^T] \boldsymbol{\phi}(\mathbf{x}') \\ &= \boldsymbol{\phi}(\mathbf{x})^T \boldsymbol{\Sigma}_p \boldsymbol{\phi}(\mathbf{x}') = k(x, x') \end{aligned}$$

- Thus  $f(\mathbf{x}_1), \dots, f(\mathbf{x}_N)$  for any  $N$  are jointly Gaussian!

$\Rightarrow f(x)$  is distributed according to GP with kernel