

UNIVERSITY OF AMSTERDAM Informatics Institute



Machine Learning 1

Lecture 12.2 - Kernel Methods Gaussian Processes - Kernelizing Bayesian Linear Regression

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(Bishop 6.4.0, 6.4.1)

Slide credits: Patrick Forré and Rianne van den Berg

Given input **x** and target *t*, we assumed

$$t = \boldsymbol{\phi}(\mathbf{x})^T \mathbf{w} + \varepsilon$$
 with $\varepsilon \sim \mathcal{N}(0, \beta^{-1})$

• So for observations $\mathbf{X} = \begin{bmatrix} \mathbf{x}_1^T \\ \vdots \\ \mathbf{x}_N^T \end{bmatrix}$ and $\mathbf{t} = \begin{bmatrix} t_1 \\ \vdots \\ t_N \end{bmatrix}$ we have Likelihood '. $\mathbf{t} = \mathbf{\Phi}\mathbf{w} + \boldsymbol{\varepsilon} , \qquad \boldsymbol{\varepsilon} \sim \mathcal{N}(\mathbf{0}, \beta^{-1}\mathbf{I}) , \qquad p(\mathbf{t} \mid \mathbf{X}, \mathbf{w}) = \mathcal{N}\left(\mathbf{t} \mid \mathbf{\Phi}\mathbf{w}, \beta^{-1}\mathbf{I}\right)$

We imposed a prior on **W**:

$$p(\mathbf{w}) = \mathcal{N}\left(\mathbf{w} \,|\, \mathbf{0}, \mathbf{\Sigma}_p\right)$$

After observing X and t, we obtained posterior

$$p(\mathbf{w} | \mathbf{X}, \mathbf{t}) = \frac{p(\mathbf{t} | \mathbf{X}, \mathbf{w}) p(\mathbf{w})}{p(\mathbf{t} | \mathbf{X})} = \mathcal{N} \left(\mathbf{w} | \mathbf{m}_N, \mathbf{S}_N \right)$$

with $\mathbf{m}_N = \beta \mathbf{S}_N^{-1} \mathbf{\Phi}^T \mathbf{t}$, $\mathbf{S}_N^{-1} = \beta \mathbf{\Phi}^T \mathbf{\Phi} + \mathbf{\Sigma}_p^{-1}$

• Predictions for new point \mathbf{x}^* , after observing N data points

$$p(t^* | \mathbf{x}^*, \mathbf{X}, \mathbf{t}) = \int p(t^* | \mathbf{x}^*, \mathbf{w}) p(\mathbf{w} | \mathbf{X}, \mathbf{t}) \, \mathrm{d}\mathbf{w}$$
$$= \mathcal{N}\left(t^* | \mu_N(\mathbf{x}^*), \sigma_N^2(\mathbf{x}^*)\right)$$

with

$$\boldsymbol{\mu}_{N}(\mathbf{x}^{*}) = \boldsymbol{\phi}(\mathbf{x}^{*})^{T} \mathbf{m}_{N} = \beta \boldsymbol{\phi}(\mathbf{x}^{*})^{T} \mathbf{S}_{N}^{-1} \boldsymbol{\Phi}^{T} \mathbf{t} = \sum_{\substack{n \equiv 1 \\ N \neq N}}^{N} \beta \boldsymbol{\phi}(\mathbf{x}^{*})^{T} \mathbf{S}_{N}^{-1} \boldsymbol{\phi}(\mathbf{x}_{n}) t_{n}$$
$$= \sum_{\substack{n \equiv 1 \\ N \neq N}}^{N} \beta \boldsymbol{\phi}(\mathbf{x}^{*})^{T} \mathbf{S}_{N} \boldsymbol{\phi}(\mathbf{x}^{*}) = \beta^{-1} + \boldsymbol{\phi}(\mathbf{x}^{*})^{T} \mathbf{S}_{N} \boldsymbol{\phi}(\mathbf{x}^{*}) = \beta^{-1} + \boldsymbol{\phi}(\mathbf{x}^{*})^{T} \mathbf{S}_{N} \boldsymbol{\phi}(\mathbf{x}^{*})$$

Mean predictions are linear combinations of kernels!



- Linear Bayesian regression suffers from limited expressiveness
 (Mear in w)
- Can become more expressive for larger M, where $\phi(\mathbf{x}) \in \mathbb{R}^M$
- However, this also requires more parameters! ($\mathbf{w} \in \mathbb{R}^M$)
- + It's expensive to train more expressive models! (requires inverting \mathbf{S}_N which is of size $M \times M$)
- We also need to choose our basis functions at 'good' locations
- But we saw that the final mean prediction can be written in equivalent kernel form...

